

# CBCS SCHEME

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## Third Semester B.E. Degree Examination, Feb./Mar. 2022 Control Systems

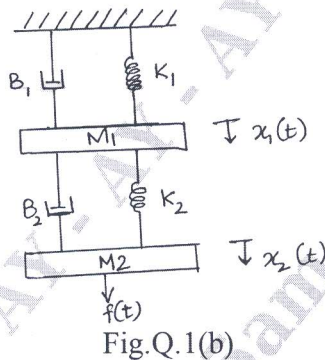
Time: 3 hrs.

Max. Marks: 100

*Note: Answer any FIVE full questions, choosing ONE full question from each module.*

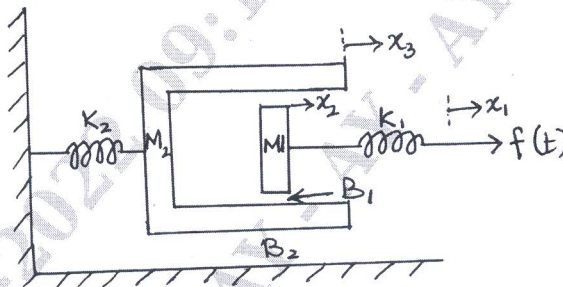
### Module-1

- 1 a. Explain the difference between open loop and closed loop control systems. Describe two example for each. (10 Marks)
- b. Obtain the transfer function for the following mechanical system shown below in Fig.Q.1(b). (10 Marks)

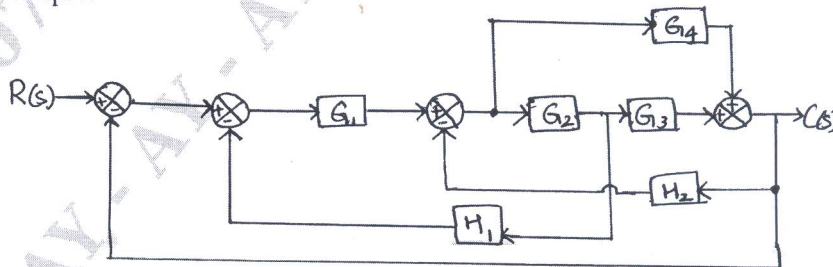


OR

- 2 a. Write the differential equations for the mechanical system shown in Fig.Q.2(a) and obtain F-V and F-I analogous electrical networks. (10 Marks)



- b. Obtain the transfer function for the block diagram shown in Fig.Q.2(b) using block diagram reduction technique. (10 Marks)



Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.  
2. Any revealing of identification, appeal to evaluator and/or equations written eg. 42+8 = 50, will be treated as malpractice.

**Module-2**

- 3 a. Discuss the terminologies used in signal flow graph shown in Fig.Q.3(a)
- i) Forward path
  - ii) Feedback loop
  - iii) Self loop
  - iv) Path gain
  - v) Non-touching loops.

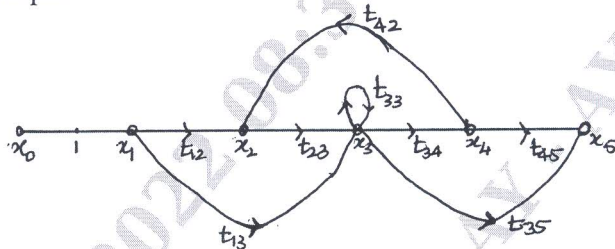


Fig.Q.3(a)

(10 Marks)

- b. For the signal flow graph of figure below, Fig.Q.3(b), determine the transfer function  $\frac{C(S)}{R(S)}$  using Mason's gain formula.

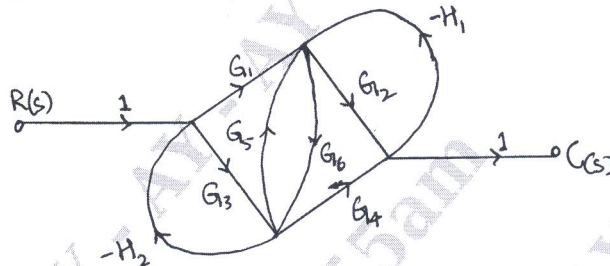


Fig.Q.3(b)

(10 Marks)

**OR**

- 4 a. Derive the expression for unit step response of under damped second order system. (10 Marks)
- b. A second order system is given by  $\frac{C(s)}{R(s)} = \frac{25}{s^2 + 6s + 25}$ , find its rise time, peak time, peak overshoot and settling time if subjected to unit step input. Also calculate expression for its output response. (10 Marks)

**Module-3**

- 5 a. Check the stability of the given characteristic equation using Routh's method:  $s^6 + 2s^5 + 8s^4 + 12s^3 + 20s^2 + 16s + 16 = 0$  (10 Marks)
- b. The block diagram of the feedback control system is shown in the Fig.Q.5(b). Apply RH criterion to determine the range of K for stability if

$$G(s) = \frac{K}{(s+4)(s+5)}$$

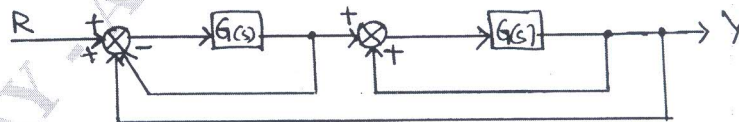


Fig.Q.5(b)

(10 Marks)

OR

- 6 a. Derive the expression for resonant peak  $M_r$  and resonant frequency  $\omega_r$  for a standard second order system in terms of  $\zeta$  and  $\omega_n$ . (10 Marks)
- b. For unity feedback system with  $G(s) = \frac{100}{s(s+5)}$  determine:
- Resonance Peak
  - Resonance frequency. (10 Marks)

**Module-4**

- 7 a. Sketch the complete root locus of system having  $G(s)H(s) = \frac{K}{s(s+1)(s+2)(s+3)}$ . (10 Marks)
- b. Explain the following as applied to the root locus:
- Centroid
  - Asymptotes
  - Breakaway points
  - Angle of departure
  - Angle of arrival. (10 Marks)

OR

- 8 a. State and explain the various frequency domain specifications. (10 Marks)
- b. i) Explain the procedure to obtain gain margin and phase margin from the bode plot. (06 Marks)
- ii) What should be values of GM and PM of a good system? (04 Marks)

**Module-5**

- 9 a. Obtain the appropriate state model for a system represented by an electric circuit in Fig.Q.9(a). (10 Marks)

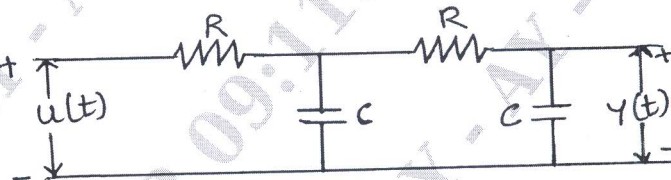


Fig.Q.9(a)

- b. Obtain the state transition matrix for the following system:

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -1 & -0.5 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0.5 \\ 0 \end{bmatrix} u$$

(10 Marks)

OR

- 10 a. i) Explain the derivation of transfer function from the state model. (08 Marks)
- ii) Explain the advantages of phase variable. (02 Marks)
- b. Find the transfer function for a system having state model as given below:

$$\dot{X} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} X + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u$$

$$Y = [1 \ 0] X.$$

(10 Marks)

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