

CBCS SCHEME

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17MT661

Sixth Semester B.E. Degree Examination, Feb./Mar. 2022

Robotics and Automation

Time: 3 hrs.

Max. Marks: 100

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- 1 a. Define Robot. Explain different types of Robot. (10 Marks)
b. Explain the various generation of Robots. (10 Marks)

OR

- 2 a. Briefly explain different configurations of Robots. (10 Marks)
b. What are degrees of freedom? With a neat sketch, explain the degrees of freedom associated with body and wrist of a polar coordinate robot. (10 Marks)

Module-2

- 3 a. Describe the various types of drive systems for Robots. (10 Marks)
b. With a neat sketch, explain the working of Range sensor and its applications. (10 Marks)

OR

- 4 a. Describe the working of various types of magnetic sensors. (10 Marks)
b. What is path planning? Describe the classification of Robots based on path control. (10 Marks)

Module-3

- 5 a. What are Grippers? Explain its general classification. (10 Marks)
b. Discuss the design consideration of Grippers. (10 Marks)

OR

- 6 a. What are End effectors? Explain different types. (10 Marks)
b. Explain the concept of force control in Robotics manipulator. (10 Marks)

Module-4

- 7 a. With a neat block diagram, explain the various elements of an automated system. (10 Marks)
b. Explain the concept of safety in Industrial Automation. (10 Marks)

OR

- 8 a. With a neat sketch, explain three levels of safety sensor systems. (10 Marks)
b. Explain the different types of automation systems and their characteristics. (10 Marks)

Module-5

- 9 a. Explain the principles of material handling. (10 Marks)
b. Explain the various storage systems in Industrial Automation. (10 Marks)

OR

- 10 a. Briefly explain material loading and unloading applications. (10 Marks)
b. Explain various types of Material Handling Equipments. (10 Marks)
